Dispatch and clustering of ancillary services from distributed storage

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1. Introduction

- 2. Dispatch of stochastic generation and distribution systems with batteries and downstream flexibility.
- 3. The benefit of dispatching stochastic power flows: a systemwise analysis.
- 4. An algorithmic framework to provide multiple ancillary services with one battery unit.
- 5. Conclusions





1

Integration of battery storage systems in electrical grids: mainstream trends

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Two operational perspectives for the integration of batteries in the grid:

- Improving system efficiency and social benefits, e.g. reducing reserve, meeting reliability levels, reducing costs, relieving congestions in transmission systems, reducing CO2 emissions (?)*.
- Increasing the hosting capacity of distribution networks for renewable generation (e.g. voltage control, congestion management, peak shaving).
- * Storage might lead to increased CO2 levels due to displacing gas in favor of coal generation, see e.g. [Lueken and Apt, 2014], [Preskill and Callaway, 2018].





Storage applications at the system level

- Energy arbitrage: buying cheap electricity and reselling at higher price (**self-defeating scheme**).
- Reserve provision, i.e. using batteries to provide reserve capacity instead of conventional generation units.
- Primary frequency control.



Applications of storage in distribution systems

- Peak-shaving, PV self-consumption.
- Grid control, i.e. congestions management with nonconvex optimal power flow, convex relaxations, or linearized OPF.



2

Dispatching stochastic generation and distribution systems with batteries and downstream flexibility

(in other words, how to seamlessly control distributed storage to help to provide services to both the local grid and the system)





Dispatching stochastic resources

• *Dispatching stochastic resources* is making sure that the aggregated active power flow of a set of heterogenous resources with stochastic output (e.g., demand + PV generation) follows a preestablished trajectory (**dispatch plan**) by controlling some flexibility.



- Relevant to reduce the need for power reserves to operate the grid (see later), as opposed to typical reserve procurement schemes (e.g., market, aggregation).
- Not totally new, e.g., proposed already for PV plants [Marinelli2014], [Conte et al., 2017] and wind farms [Abu2015].
- Extended to heterogeneous resources in [Sossan2016], [Appino2018].



Dispatching distribution systems [Sossan2016]

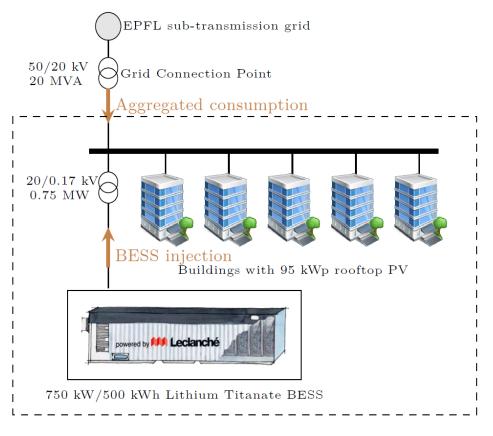


Figure: Topology of the dispatchable feeder at EPFL.

Problem Statement

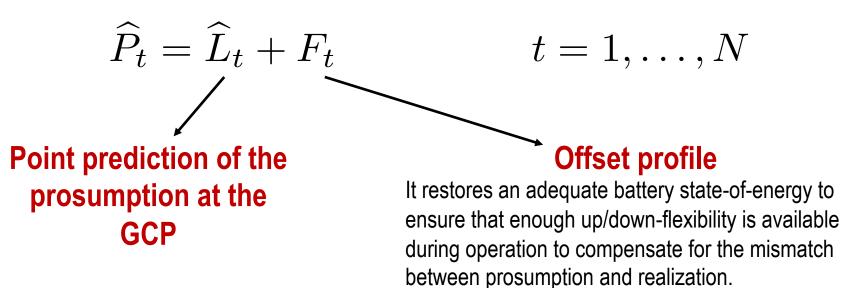
- 1. Computing dispatch plan with given resolution, look-ahead time, and period.
- 2. Controlling flexibility (e.g., a gridconnected battery) in real-time to track the dispatch plan.



Definition of dispatch plan [Sossan2016]

The **dispatch plan** is a series at a certain time resolution and look-ahead horizon (say 5 minutes and 24 hours) of the scheduled active power flow at the GCP.

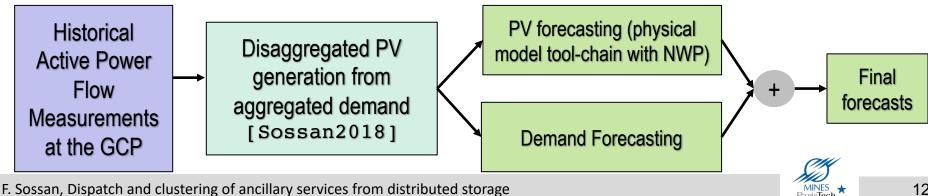
It is defined as:





Dispatch plan: point predictions of the 'prosumption'

- Forecasting stochastic demand/generation is a well-established practice. It is however challenging when at a high level of disaggregation (e.g., at low or medium voltage levels) du to high volatility and non-stationarity of the series.
- ARIMAX-class models generally fails in capturing highly disaggregated prosumption profiles.
- Non-parametric methods found to be perform better than parametric ones.
- In distribution networks with large presence of distributed PV generation, accounting for irradiance patterns is key for good performance.
- Our proposed way:

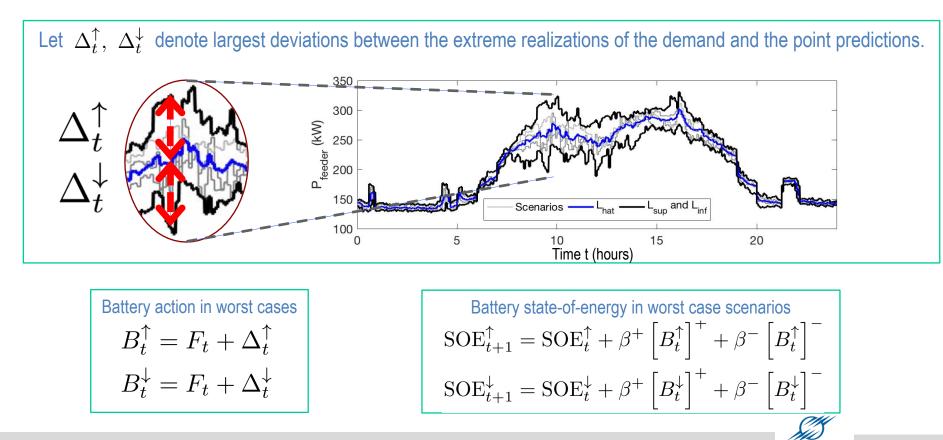


Dispatch plan: computation of the offset profile

During operation at time *i*, the battery compensates for the mismatch between dispatch plan \hat{P}_t and stochastic realization L_t . The battery injection is:

$$B_t = \widehat{P}_t - L_t$$
 by applying the dispatch plan definition

$$B_t = F_t + \widehat{L}_t - L_t$$



Dispatch plan: computation of the offset profile - cont'd

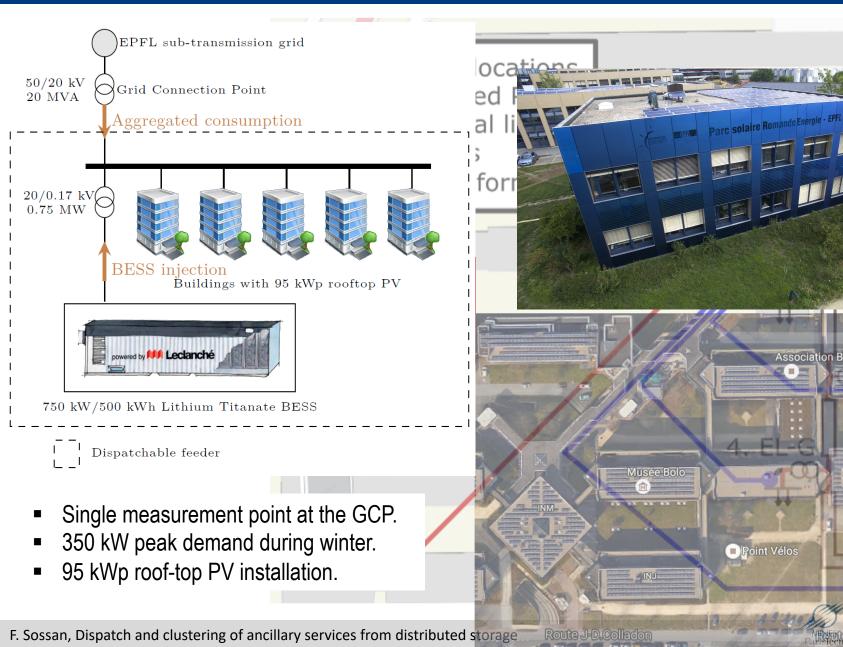
With Δ_t^{\uparrow} , Δ_t^{\downarrow} given, we seek an offset profile F = [F1, ..., FN] so that the battery's state-of-energy and power injection are within limits:

$$\begin{aligned} F^{o} &= \mathop{\arg\min}_{F \in \mathbb{R}^{N}} \left\{ \sum_{t=1}^{N} F_{t}^{2} \right\}^{\substack{\text{Sequence with least norm-2 (arbitrary, it could be just a feasibility problem)}} \\ &\text{subject to (for } t = 0, 1, \dots, N-1): \\ B_{t}^{\uparrow} &= F_{t} + \Delta_{t}^{\uparrow} \\ B_{t}^{\downarrow} &= F_{t} + \Delta_{t}^{\downarrow} \\ &\text{SOE}_{t+1}^{\uparrow} = \text{SOE}_{t}^{\uparrow} + \beta^{+} \left[B_{t}^{\uparrow} \right]^{+} + \beta^{-} \left[B_{t}^{\uparrow} \right]^{-} \\ &\text{SOE}_{t+1}^{\downarrow} = \text{SOE}_{t}^{\downarrow} + \beta^{+} \left[B_{t}^{\downarrow} \right]^{+} + \beta^{-} \left[B_{t}^{\downarrow} \right]^{-} \\ &\text{Worst case lowest state-of-energy must be higher than minimum allowed} & \underbrace{\text{SOE}_{t+1}^{\downarrow} \geq \text{SOE}_{\text{max}}}_{B_{t}^{\downarrow} \geq B_{\text{min}}} \\ &B_{t}^{\downarrow} \geq P_{\text{max}} \end{aligned}$$

(nonconvex due to the sign operators, can be convexified as done in the paper)



Validation: experimental setup



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Validation: battery energy storage system

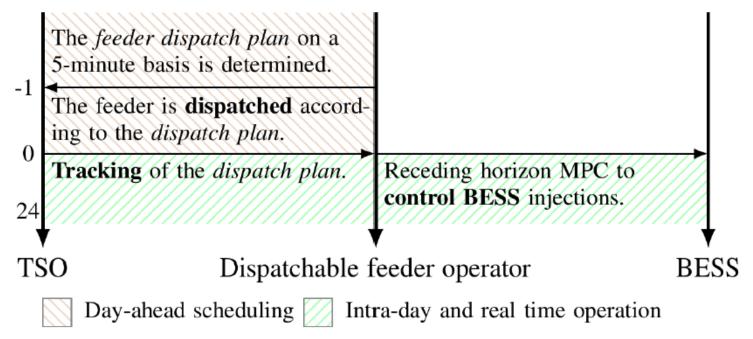
Parameter	Value
Nominal Capacity	720 kVA/560 kWh
GCP Voltage	20 kV
DC Bus Voltage Range	600/800 V
Cell Technology (Anode/Cathode)	Lithium Titanate Oxide (LTO) Nichel Cobalt Alumnium Oxide (NCA)
Number of racks	9 in parallel
Number of modules per rack	15 in series
Cells configuration per module	20s3p
Total number of cells	8100
Cell nominal voltage	2.3 V (limits 1.7 to 2.7 V)
Cell nominal capacity	30 Ah (69 Wh)
Round-trip efficiency (AC side)	94-96%
Round-trip efficiency (DC side)	97-99%





Validation: implementation and operation

Time (hours before the beginning of the day of operation)

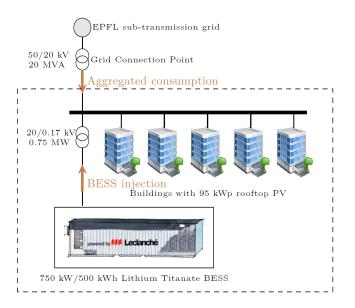




Validation: experimental results

- Dispatch on Jan 14, 2016 https://snapshot.raintank.io/dashboard/snapshot/PuW1Rf5d47000gsT7UNponM25bGDNTF
- Dispatch on Jan 13, 2016 https://snapshot.raintank.io/dashboard/snapshot/cDS4IDniZjRiePXvusnmQXOmMwpGLnR6
- Dispatch with peak-shaving on Jun 22, 2016
- Dispatch with load levelling on Mar 14, 2016 https://snapshot.raintank.io/dashboard/snapshot/4ztn800czpAzEFRzbGOmWc1A2pKeC9ab
- Dispatch from Jun 16 to 19, 2016

https://snapshot.raintank.io/dashboard/snapshot/TNbEgP7j1AWhaW7cEK1ZiK3tY10r7P4U





Extension to multiple controllable resources

What if we have multiple flexible elements in the mix (e.g. battery, flexible demand and curtailable renewable generation)?

They all concur in achieving the dispatch control problem. In brief, the formulation can be extended by:

- Compute one dispatch plan per each element in the mix [Fabietti et al., 2018].
- The dispatch plan at the GCP is the algebraic sum of the individuals dispatch plans (eventually with losses, see [Stai, et al., 2018]).
- The real-time control problem with multiple controllable elements is distributable (<u>tractable</u>) [Fabietti et al., 2017] [Gupta et al., 2018].





The benefit of dispatching stochastic power flows: a system-wise analysis





System validation [Bozorg2018]

What if dispatching distribution systems is applied as a mechanism to achieve implicit coordination between load balance responsible and aggregators?

A Monte Carlo simulation framework to simulate reserve activation as a function of the grid frequency and load shedding. Generate a random scenario for stochastic generation and demand Calculate system frequency after PFR Power: regulation capacity vs demand 5 3 5 $-2.5 \text{ Hz} \overline{G_g} \ge \sum N_b^s \sum \underline{G_g} \le \sum N_b^s$ 2.5 Hz $\sum \overline{G_g} \leq \sum N_b^s \sum \underline{G_g} \geq \sum N_b^s$ Freq. deviation Frequency Frequency collapse collapse from nominal Under Frea. Non-controllable Load shedding collapse 1, 2, and 3 4, and 5 Stable operation System Collapse Calculate Expected Load Not Served (ELNS)

We measure the impact of dispatching vs nondispatching by measuring the amount of **energy not served** in a large power system.

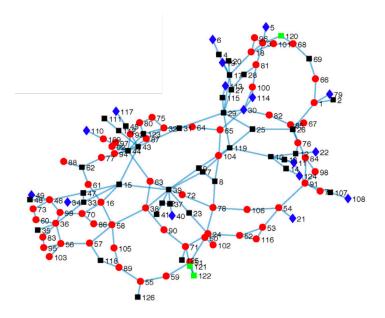


Figure. Case study:126-bus Western Danish transmission system (400, 165 kV).



System validation [Bozorg2018]

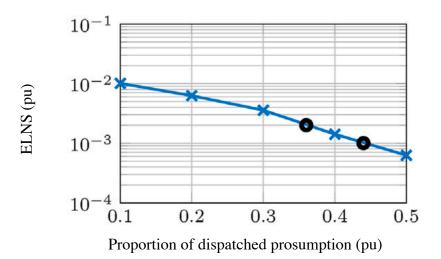


Fig.: Energy not served vs proportion of dispatched prosumption \rightarrow increasing dispatch improves reliability.

We use a model from the literature to assess the cost of the regulating and calculate the economic pay-back time.

(*) Skytte, K., 'An econometric analysis for the regulating power market', 1999.

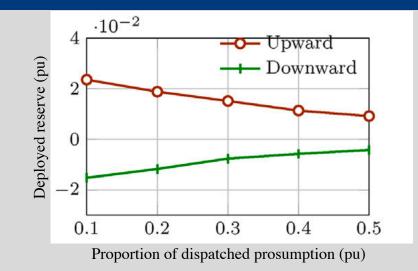
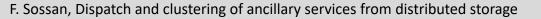


Fig.: Deployed power reserves vs penetration of dispatchable feeders at constant energy reserve.



Fig.: Operational costs and pay-back time at .5 dispatched presumption → pay-back time is compatible with storage life-time.

An algorithmic framework to provide multiple ancillary services with one battery unit





Provision of multiple ancillary services [Namor2018]

Single-service applications might underuse battery's power rating and energy capacity:

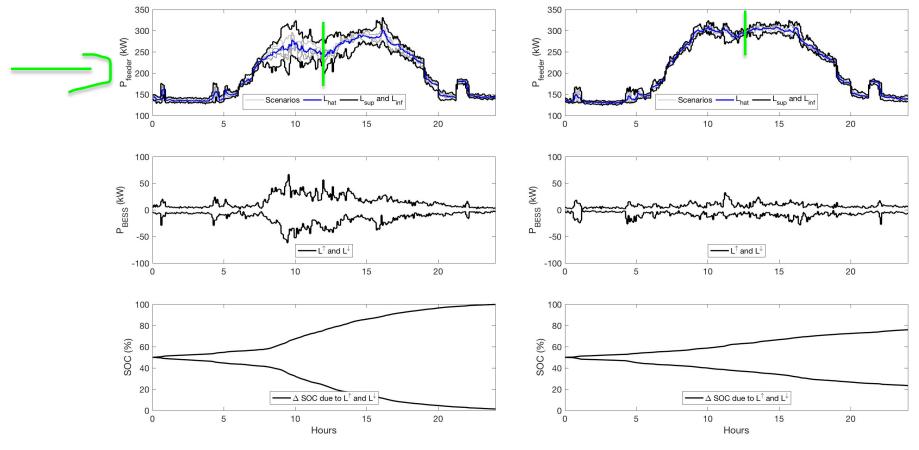


Fig.: Dispatch with high uncertainty.

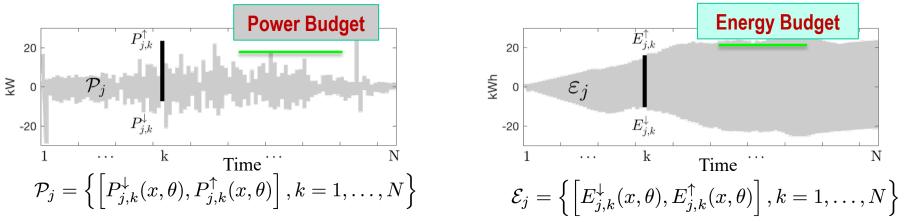
Fig.: Dispatch with low uncertainty.

Residual power/energy capacity can be used to provide multiple ancillary services simultaneously.



Algorithm for stacking ancillary services

We have multiple services to provide. We define for each grid ancillary service *j* the:



parametrized over vector of controller's parameters x and forecast of the unitary budgets θ .

Operator to determine width of envelopes: $w(\mathcal{E}_j(x,\theta)) \triangleq \{E_{j,k}^{\uparrow}(x,\theta) - E_{j,k}^{\downarrow}(x,\theta), k = 1, \dots, N\}$

We seek to find the controllers' parameters which maximize the exploitation of the battery energy capacity subject to the battery's power and energy constraints.

$$\arg\max_{x} \left\| w(\sum_{j} \mathcal{E}_{j}(x,\theta)) \right\|_{1}$$

subject to:

$$E_{init} + \sum_{j} \mathcal{E}_{j}(x,\theta) \in [E_{min}, E_{max}]$$
$$\sum_{j} \mathcal{P}_{j}(x,\theta) \in [-P_{max}, P_{max}]$$



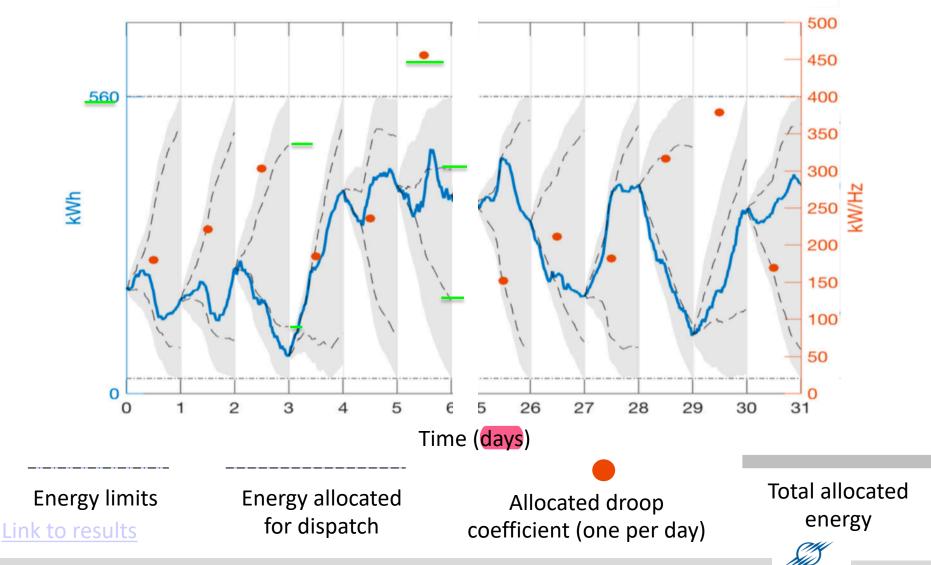
Dispatch + primary frequency regulation (PFR)

	Dispatch	PFR
Power Budget	Worst case high and worst case low power deviation from the dispatch plan.	Drop coefficient (unknown, to determine) time worst case frequency deviation (200 mHz).
Energy Budget	Integral of worst case deviations.	5-95% quantiles of the distribution of the accumulated frequency deviation in 1 day over a 2-year period.



Stacking ancillary services: Results

Day-ahead scheduling for dispatch and primary frequency control



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Conclusions

- Dispatching stochastic prosumption by using downstream flexibility achieves to reduce reserve requirements.
- Cost effective: pay-back time is shorter than storage life.
- It can be regarded to as a way to achieve efficient coordination between DSOs and load balance responsible.
- We outlined an algorithmic framework to provide multiple ancillary services with the same battery.



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Thanks for your attention!



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